

Dynamic Lane Merge Systems

International Road Dynamics Inc.







Acknowledgements



- Maryland State Highway Administration
- University of Maryland, College Park
- Michigan Department of Transportation
- Wayne State University





Lane Merging Issues



- Merging traffic → Traffic conflict
 - Solution
 Solution
 - Speed variance
 - Oriver frustration
 - Safety concerns
 - Increased delay
- Approaches to merge control
 - . Merge late
 - . Merge early









Goal: Improve safety and mobility through intelligent traffic guidance

- Static signing may lack relevance
- Traffic conditions are not constant
- Appropriate traffic control is not constant
- Relevant control for current conditions
 - Clear and positive guidance
 - Fairness
 - Safety





Dynamic Late Merge System



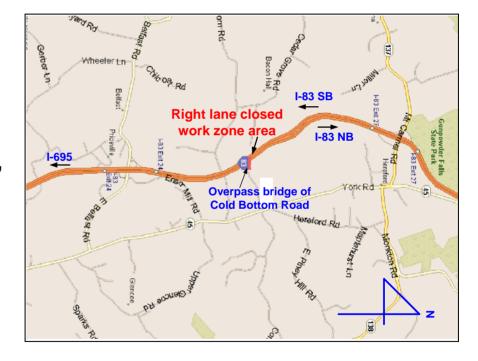
Project Location

Southbound I-83 near Cold Bottom Road

Project Duration

October 13 to November 17, 2003

Project Evaluation
 University of Maryland

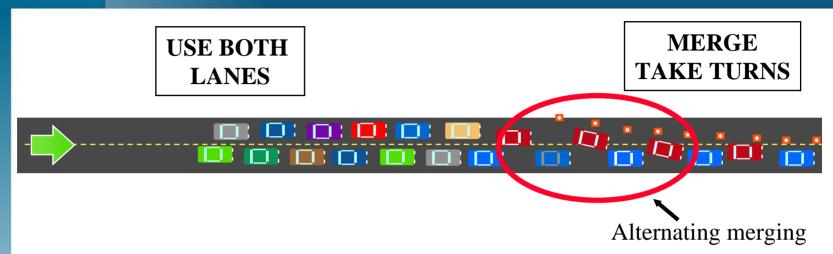






Late Merge Concept





- Use both lanes to taper area
- "Zipper" at taper vehicles alternate from each lane
- With static signs
 - May improve flow under congested conditions
 - Conflict and confusion during mild congestion





Overview of A Dynamic Late Merge System

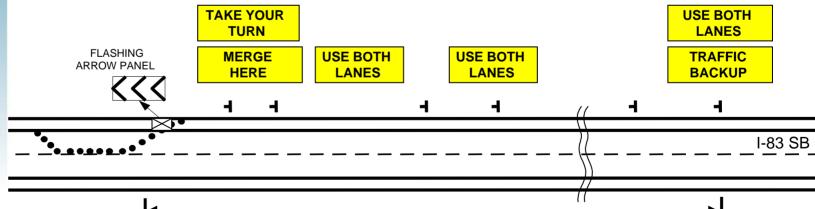












Approx. 7400'

Overview of A Dynamic Late Merge System

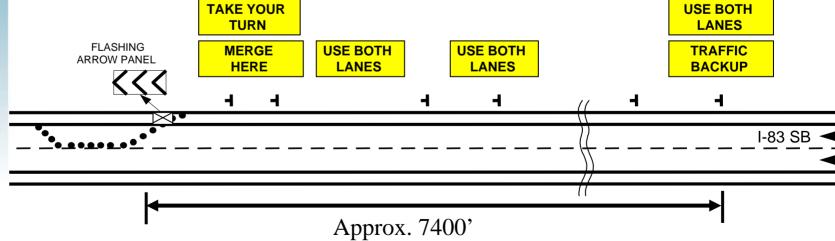




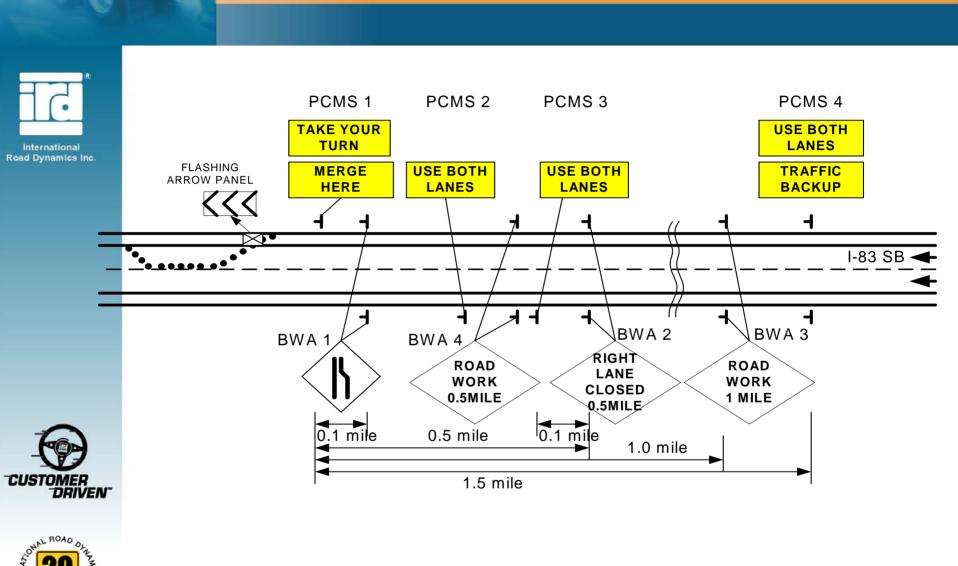








Overview of A Dynamic Late Merge System



Late Merge System Control



- Four algorithms available for control of late merge implementation
- "All On All Off" tested on this project

Algorithm	Occupancy		
Algorithm	Activated	Deactivated	
Dynamic On – Dynamic Off (Sign 1 always on)			
Dynamic On – Dynamic Off	Any > 15% (Congestion	All < 5%	
All On – All Off	index)	(Free flow index)	
Dynamic On – All Off			

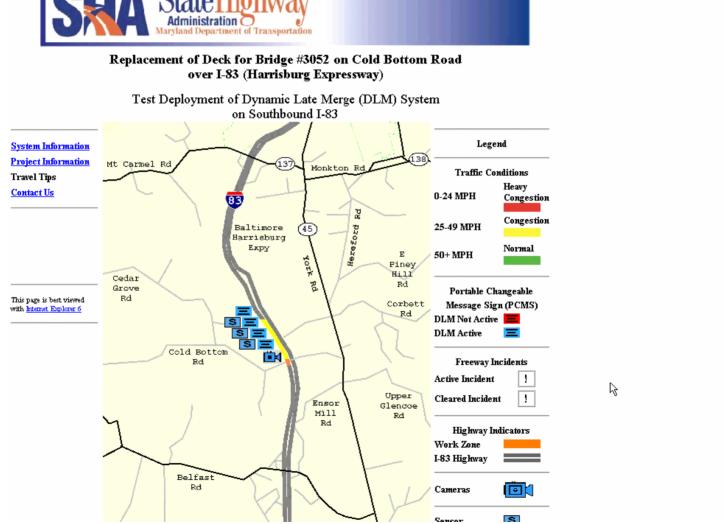




Public Website

- B ×







CUSTOMER

http://tis.irdinc.com/i83construction/public

Video Trailer











TOC-3

Camera Web Page





Position 2

Position 3

Position 4

Position 5

Camera #1



Save Current Camera Position

Position 1

Position 2

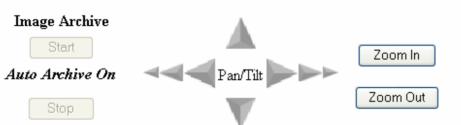
Position 3

Position 4

Position 5







Close

Wiper Control

Activate

Travel Information



















Measures of Effectiveness:

- Work zone throughputs (vehicles / hour)
 - The DLM system is expected to show more throughput than under No-control system.
- Lane volume distributions (volume difference)
 - The DLM system is expected to make most vehicles use both lanes uniformly until they approach the merging point.
- Maximum queue lengths (miles)
 - The uniformed lane distributions are expected to lead to a reduction on maximum queue length.







Two Methods:

- Manual counted data analysis
 - Work zone throughputs and lane volume distributions
- Simulation data analysis: to overcome the limitations that the traffic volumes under No-control and DLM control are not identical, and that the view scope of camcorders may not always capture the maximum queue length.
 - Work zone throughputs and maximum queue length







Work zone throughputs

- Manual counts: most work zone throughputs are greater than without dynamic late merge.
- Simulation: work zone throughputs are at least 10 % greater than without dynamic late merge.







Lane Volume Distributions (Volume at open lane) – (volume at closed lane)

		Merging Point		Middle Point		Upstream Point	
	Date	Average difference [pcph]	Standard deviation	Average difference [pcph]	Standard deviation	Average difference [pcph]	Standard deviation
	10/10/2003	1297	158	199	168	-26	122
	10/22/2003	1207	249	122	200	No data	
	10/23/2003	1114	159	17	126	-47	125
-	11/07/2003	901	208	1	146	-69	136
	11/10/2003	932	174	-4	150	-162	143





- The lane volume distributions are more uniform than under no-control (both at the middle and merging points).
- More drivers followed the message sign (i.e., "USE BOTH LANES TO MERGE POINT") displayed on the PCMSs under the congested traffic condition.
- Many drivers decided to merge at the static merge sign located upstream of the taper area.





Evaluation of System Performance



Based on simulation, substantial reduction in queue length

Date	Actual queue (DLM)	Simulated queue (NC)	Reduced %
10/22/2003	1.2 miles	1.3 miles	8.3%
10/23/2003	1.2 miles	1.4 miles	16.7%
11/07/2003	1.8 miles	2.0 miles	11.1%
11/10/2003	0.9 miles	1.2 miles	33.3%







- Advantages of a Dynamic Late Merge Control
 - Increases throughput
 - Leads to a more uniform volume distribution
 - Reduces the maximum queue length
- Disadvantages of a Dynamic Late Merge Control
 - Stop-and-go maneuvers may increase
 - Multiple merging locations experienced





Early Merge Approach



Dynamic Early Merge Approach

- Merging during congestion is more difficult
- Merge under free flow and low density conditions
- Deter queue jumpers
- Relevant to current conditions





Dynamic Early Merge System Operation







Dynamic Early Merge Trailer





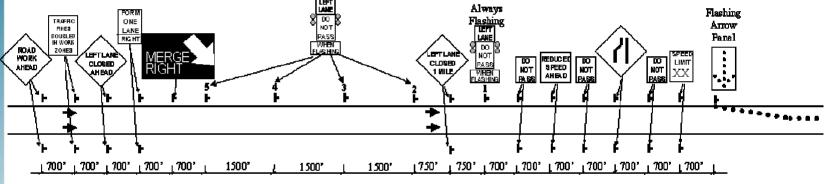
I-69 Near Lansing, Michigan

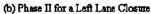




Typical Layout







LE GEND

- Type A Warning Flasher (Required at Night)
- Type B High Intensity Light
- Traffic Flow





Michigan Early Merge Evaluation



- Two year study completed by Wayne State University in December 2001
- Implementation of dynamic lane merge system at 6 locations to study deployment issues and effectiveness
- Phase I (2000) Deployment and configuration
- Phase II (2001) Effectiveness





Evaluation of Dynamic Early Merge



- Examined best configuration for positive guidance to motorists
- Measured impact of system on traffic
- Provided recommendations for future deployments
- Conclusion: "Can be very helpful in reducing aggressive driver behavior, increasing safety and reducing delay at work zones where lane closures are necessary."





Evaluation of Dynamic Early Merge



- The average peak period travel time decreased by over 30%
- The average number of stops and duration of stops were decreased
- The number of aggressive driver maneuvers (late merges) during peak hours were reduced by 50-75%
- B/C (Benefit/Cost) ratio is greater than one, if the value of time of \$3.80 per person hour is assumed for travel time savings





Conclusion



One goal – improved safety and mobility

- Current and relevant positive guidance to motorists
- Both approaches have potential benefits
- Best approach will depend on specific conditions







Thank You

International Road Dynamics Inc.





